

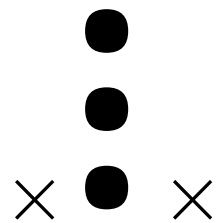
Declarative Action Programs

- Agent Logic Programs
- Semantics
- Fast State Update in Prolog
- Wumpus, Sensing, and Constraint Logic Programming

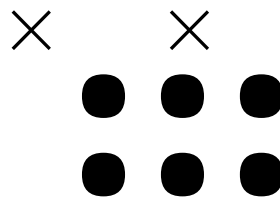
Example: Peg Solitaire

		74	75	76		
	63	64	65	66	67	
52	53	54	55	56	57	58
42	43	44	45	46	47	48
32	33	34	35	36	37	38
	23	24	25	26	27	
		14	15	16		

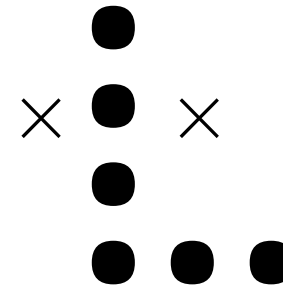
An Agent Logic Program (ALP)



3-pattern



6-pattern



L-pattern

```
is_pattern([C, X1, X2, X3]) :- ?(peg(C)),  
                                X1 = C+1, X2 = X1+10, X3 = X1+20,  
                                ?(peg(X1) and peg(X2) and peg(X3)).
```

```
is_pattern([C, X1, X2, X3]) :- ?(peg(C)),  
                                X1 = C-1, X2 = X1+10, X3 = X1+20,  
                                ?(peg(X1) and peg(X2) and peg(X3)).
```

...

ALP for Peg Solitaire (Cont'd)

```
board_solved :- ?(peg(45) and forall(X, X=45 or not peg(X))).
```

```
pattern_solved(P) :- member(Y,P), do(jump(U,V,W)),  
    pattern_solved(P).
```

```
pattern_solved([Catalyst|P]) :- ?(peg(Catalyst)), empty(P).
```

```
empty([]).
```

```
empty([X|L]) :- ?(not peg(X)), empty(L).
```

```
strategy :- board_solved.
```

```
strategy :- is_pattern(P), pattern_solved(P), strategy.
```

ALP Syntax

- Terms of sort FLUENT and ACTION
- If $p?$ is an n -ary relation and t_1, \dots, t_n are terms, then $p(t_1, \dots, t_n)$ is a **program atom**
- If a is an ACTION term, then $do(a)$ is a **program atom**
- If ϕ is a state property composed of FLUENT terms, then $?(\phi)$ is a **program atom**
- If H, B_1, \dots, B_n are program atoms, then $H : -B_1, \dots, B_n$ is an **ALP clause**
- An **ALP** is a finite set of ALP clauses
- An **ALP query** is a finite sequence of program atoms

Declarative Semantics

Clause and Query Expansion

For a clause $H: -B_1, \dots, B_n$ let s_1, \dots, s_{n+1} be a sequence of TIME variables.

- For $i = 1, \dots, n$
 - If B_i is of the form $p(t_1, \dots, t_m)$, it is expanded to $p(t_1, \dots, t_m, s_i, s_{i+1})$;
 - If B_i is of the form $do(a)$, it is expanded to $Poss(a, s_i, s_{i+1})$;
 - If B_i is of the form $?(ϕ)$, it is expanded to $ϕ[s_i]$ and $s_{i+1} = s_i$.
- The head $H = p(t_1, \dots, t_m)$ is expanded to $p(t_1, \dots, t_m, s_1, s_{n+1})$.
- “: -” is replaced by “ \subset ” and “,” is replaced by “ \wedge ”.
- A query is expanded like the body of a clause but with s_1 set to the initial TIME constant.

Example

```
strategy :- board_solved.
```

```
strategy :- is_pattern(P), pattern_solved(P), strategy.
```

is expanded to

$$\textit{Strategy}(s_1, s_2) \subset \textit{BoardSolved}(s_1, s_2)$$
$$\textit{Strategy}(s_1, s_4) \subset \textit{IsPattern}(p, s_1, s_2) \wedge \textit{PatternSolved}(p, s_2, s_3) \wedge \textit{Strategy}(s_3, s_4)$$

```
board_solved :- ?(peg(45) and forall(X, X=45 or not peg(X))).
```

is expanded to

$$\textit{BoardSolved}(s, s) \subset \textit{Holds}(\textit{Peg}(45), s) \wedge (\forall x) (x = 45 \vee \neg \textit{Holds}(\textit{Peg}(x), s))$$

Importance of Atom Ordering

$p :- ?(f), do(a).$

is expanded to

$$P(s_1, s_2) \subset Holds(F, s_1) \wedge Poss(A, s_1, s_2)$$

$p :- do(a), ?(f).$

is expanded to

$$P(s_1, s_2) \subset Poss(A, s_1, s_2) \wedge Holds(F, s_2)$$

Requirements for Time Structure (1)

Action execution in ALPs is strictly sequential.

Therefore the time structure must satisfy

$$Poss(a, s, t) \supset s < t$$

$$Poss(a, s, t) \wedge Poss(a', s', t') \supset (t < t' \supset t \leq s') \wedge (t = t' \supset a = a' \wedge s = s')$$

Note: This is always true when situations are used.

Requirements for Time Structure (2)

There are no “gaps” in between action executions.

Therefore the time structure must satisfy

$$(\exists t) \text{Poss}(a, s, t) \wedge (\forall f) (\text{Holds}(f, s) \equiv \text{Holds}(f, s')) \supset (\exists t') \text{Poss}(a, s', t')$$

Note: This is always true when situations are used.

Example for “Gaps”

$p \text{ :- do}(a), \text{ do}(b)$ is expanded to

$$P(s_1, s_3) \subset Poss(A, s_1, s_2) \wedge Poss(B, s_2, s_3)$$

With the precondition axioms

$$Poss(A, s, t) \equiv s = 0 \wedge t = 1$$

$$Poss(B, s, t) \equiv s = 2 \wedge t = 3$$

there is no derivation for query p

Procedural Semantics

Derivation Rules (1)

- Standard atoms:

$$\frac{Q_1 \wedge Q_2 \wedge \dots \wedge Q_n}{(B_1 \wedge \dots \wedge B_m \wedge Q_2 \wedge \dots \wedge Q_n)\theta}$$

where Q_1 is a literal defined in the ALP and $H \subset B_1 \wedge \dots \wedge B_m$ is the expansion of a clause in the ALP such that $Q_1\theta = H\theta$, for some substitution θ

Derivation Rules (2)

- Actions:

$$\frac{Poss(a, s, t) \wedge Q_2 \wedge \dots \wedge Q_n}{(Q_2 \wedge \dots \wedge Q_n)\theta}$$

where $\Sigma \models Poss(a, s, t)\theta$ with substitution θ on the variables in $Poss(a, s, t)$

- Tests:

$$\frac{\phi[s] \wedge Q_2 \wedge \dots \wedge Q_n}{(Q_2 \wedge \dots \wedge Q_n)\theta}$$

where $\Sigma \models \phi[s]\theta$ with substitution θ on the variables in ϕ

Example

```
office(alice, 101).
```

```
office(bob, 102).
```

```
deliver :- ?(has_package_for(P)), office(P,R), do(go(R)).
```

The expansion is

Office(Alice, 101, s, s)

Office(Bob, 102, s, s)

$Deliver(s_1, s_3) \subset Holds(HasPackageFor(p), s_1) \wedge Office(p, r, s_1, s_2) \wedge Poss(Go(r), s_2, s_3)$

A Successful Derivation

Deliver(S_0, s)

Holds(*HasPackageFor*(p), S_0) \wedge *Office*(p, r, S_0, s_2) \wedge *Poss*(*Go*(r), s_2, s)

Office(*Bob*, r, S_0, s_2) \wedge *Poss*(*Go*(r), s_2, s)

Poss(*Go*(102), S_0, s)

□

where we assume the precondition axiom $Poss(Go(r), s, t) \equiv t = Do(Go(r), s)$

Soundness

Theorem

If there exists a successful derivation for Q with computed answer θ then the domain axiomatization and the expanded program together entail $Q\theta$, provided the reasoner for the domain axiomatization is correct.

Incompleteness

$p :- ?(f) .$

$p :- ?(\text{not } f) .$

The expansion

$P(s, s) \subset \text{Holds}(F, s)$

$P(s, s) \subset \neg \text{Holds}(F, s)$

entails $(\exists s) P(S_0, s)$ but there is no derivation for query p .

ALPs in Prolog: Fast State Update

Piece-Wise Update vs. State Update

A problem with the direct use of successor state axioms in GOLOG – or GDL effect axioms – is that update is computed piecewise for each state property.

```
next (peg (W) ) :- does (P, jump (U, V, W) ) .  
next (peg (X) ) :- true (peg (X) ) ,  
                    does (P, jump (U, V, W) ) ,  
                    distinct (X, U) , distinct (X, V) .
```

It is often more efficient to compute entire state updates.

```
[peg (14) , . . . , peg (43) , peg (44) , peg (46) , . . . ]  
→ [peg (14) , . . . , peg (45) , peg (46) , . . . ]
```

A State-Based Description Language

A triple (F, \circ, \emptyset) is a **fluent calculus** state signature if

- F finite, non-empty set of function symbols into sort FLUENT
- $\circ : \text{STATE} \times \text{STATE} \mapsto \text{STATE}$
- $\emptyset : \text{STATE}$

A fluent is a term of sort FLUENT.

A state is a term of sort STATE, with FLUENT being a sub-sort of STATE.

Foundational Axioms

$$\text{Holds}(f : \text{FLUENT}, z : \text{STATE}) \stackrel{\text{def}}{=} (\exists z' : \text{STATE}) z = f \circ z'$$

The foundational axioms Σ are

1. **Associativity and commutativity**

$$(z_1 \circ z_2) \circ z_3 = z_1 \circ (z_2 \circ z_3) \qquad z_1 \circ z_2 = z_2 \circ z_1$$

2. **Empty state axiom** $\neg \text{Holds}(f, \emptyset)$

3. **Irreducibility** $\text{Holds}(f_1, f) \supset f_1 = f$

4. **Decomposition** $\text{Holds}(f, z_1 \circ z_2) \supset \text{Holds}(f, z_1) \vee \text{Holds}(f, z_2)$

5. **State Equality** $(\forall f)(\text{Holds}(f, z_1) \equiv \text{Holds}(f, z_2)) \supset z_1 = z_2$

6. **State Existence** $(\forall P)(\exists z)(\forall f)(\text{Holds}(f, z) \equiv P(f))$

Finite States

A **finite state** τ is a term $f_1 \circ \dots \circ f_n$ such that each $f_i (1 \leq i \leq n)$ is a fluent ($n \geq 0$).

If $n = 0$, then τ is \emptyset . A ground state is a finite state without variables.

Proposition

Let $\tau = f_1 \circ \dots \circ f_n$ be a finite state ($n \geq 0$), then

$$\sum \models Holds(f, \tau) \equiv \bigvee_{i=1}^n (f_i = f)$$

Fluent Addition and Removal

- $z_1 + f = z_2 \stackrel{\text{def}}{=} z_2 = z_1 \circ f$
- $z_1 - f = z_2 \stackrel{\text{def}}{=} (z_2 = z_1 \vee z_2 + f = z_1) \wedge \neg \text{Holds}(f, z_2)$

$z = \text{Peg}(14) \circ \dots \circ \text{Peg}(43) \circ \text{Peg}(44) \circ \text{Peg}(46) \circ \dots - \text{Peg}(43) - \text{Peg}(44) + \text{Peg}(45)$

$\rightarrow z = \text{Peg}(14) \circ \dots \circ \text{Peg}(45) \circ \text{Peg}(46) \circ \dots$

Fluent Calculus Signatures

A tuple $S \cup \langle A, S_0, Do, State, Poss \rangle$ is a **fluent calculus** signature if

- S state signature
- A finite, non-empty set of function symbols into sort ACTION
- $S_0 : \text{SIT}$
- $Do : \text{ACTION} \times \text{SIT} \mapsto \text{SIT}$
- $State : \text{SIT} \mapsto \text{STATE}$
- $Poss : \text{ACTION} \times \text{STATE}$

State and Situation Formulae

$$\text{Holds}(f,s) \stackrel{\text{def}}{=} \text{Holds}(f,\text{State}(s))$$

Definition

A **state formula** $\Delta(z)$ is a first-order formula with free state variable z and without any occurrence of states other than in expressions of the form $\text{Holds}(f, z)$, and without actions or situations.

If $\Delta(z)$ is a state formula and s a situation variable, then $\Delta(z)\{z/\text{State}(s)\}$ is a **situation formula**, written $\Delta(s)$.

Precondition Axioms

A precondition axiom for an action A is a formula

$$Poss(A(\vec{x}), z) \equiv \Pi(z)$$

where $\Pi(z)$ is a state formula with free variables among \vec{x} , z .

$$Poss(a, s) \stackrel{\text{def}}{=} Poss(a, State(s))$$

$$Poss(Jump(u, v, w), z) \equiv Holds(Peg(u), z) \wedge Holds(Peg(v), z) \wedge \neg Holds(Peg(w), z) \wedge IsBoardCell(w)$$

State Update Axioms

A **state update axiom** for an action A is a formula

$$\text{Poss}(A(\vec{x}), s) \supset (\exists \vec{y}_1)(\phi_1(s) \wedge \text{State}(\text{Do}(A(\vec{x}), s)) = \text{State}(s) - \mathfrak{g}_1^- + \mathfrak{g}_1^+) \\ \vee \dots \vee$$

where

$$(\exists \vec{y}_n)(\phi_n(s) \wedge \text{State}(\text{Do}(A(\vec{x}), s)) = \text{State}(s) - \mathfrak{g}_n^- + \mathfrak{g}_n^+)$$

- $n \geq 1$

- for $i = 1, \dots, n$,

- $\phi_i(s)$ is situation formula with free variables among \vec{x}, \vec{y}_i, s

- $\mathfrak{g}_i^+, \mathfrak{g}_i^-$ are finite states with variables among \vec{x}, \vec{y}_i

The terms $\mathfrak{g}_i^+, \mathfrak{g}_i^-$ are called, respectively, positive and negative effects of $A(\vec{x})$ under condition $\phi_i(s)$. Empty positive or negative effects are omitted.

State Update Axioms and the Frame Problem

Proposition

Under the foundational axioms it follows that

$$State(t) = State(s) - g_1 - \dots - g_m + f_1 + \dots + f_n$$

implies

$$Holds(f,t) \equiv [f = f_1 \vee \dots \vee f = f_n] \vee [Holds(f,s) \wedge f \neq g_1 \wedge \dots \wedge f \neq g_m]$$

Example: Peg Jump

$Poss(Jump(u,v,w),s) \supset$

$State(Do(Jump(u,v,w),s) = State(s) - Peg(u) - Peg(v) + Peg(w)$

State Update in Prolog

```
holds(F, Z) :- member(F, Z).
```

```
holds(F, [F|Z], Z).
```

```
holds(F, Z, [F1|Z2]) :- Z=[F1|Z1], F\==F1, holds(F, Z1, Z2).
```

```
minus(Z, [], Z).
```

```
minus(Z, [F|Fs], Z2) :- holds(F, Z, Z1), minus(Z1, Fs, Z2).
```

```
minus(Z, [F|Fs], Z2) :- not member(F, Z), minus(Z, Fs, Z2).
```

```
plus(Z, [], Z).
```

```
plus(Z, [F|Fs], Z2) :- not member(F, Z), plus([F|Z], Fs, Z2).
```

```
plus(Z, [F|Fs], Z2) :- member(F, Z), plus(Z, Fs, Z2).
```

```
update(Z1, ThetaP, ThetaN, Z2) :- minus(Z1, ThetaN, Z),  
                                   plus(Z, ThetaP, Z2).
```


Example

```
init(Z0) :- Z0 = [peg(14), ..., peg(43), peg(44), peg(46), ...].
```

```
state_update(Z1, jump(U, V, W), Z2) :-  
    update(Z1, [peg(W)], [peg(U), peg(V)], Z2).
```

```
?- init(Z0), do(jump(43, 44, 45), Z0, Z1).
```

```
Z2 = [peg(45, peg(14), ..., peg(46), ...]
```

Online / Offline Execution

- Online execution of an ALP means that the agent actually performs each action and updates (**progresses**) its state

```
do(A, Z1, Z2) :- perform(A), state_update(Z1, A, Z2).
```

- Offline execution of an ALP means that the agent searches for a successful sequence of actions (a situation) while progressing its state

```
do(Z1, S1, A, Z2, S2) :- state_update(Z1, A, Z2),  
                        S2 = do(A, S1).
```

Example ALP (Online Execution; cf.Slide 4)

```
board_solved(Z,Z) :- holds(peg(45) and
                          forall(X, X=45 or not peg(X)),Z) .

pattern_solved(P,Z1,Z4) :- member(Y,P,Z1,Z2),
                           do(jump(U,V,W),Z2,Z3),
                           pattern_solved(P,Z3,Z4) .

pattern_solved([Catalyst|P],Z1,Z2) :- holds(peg(Catalyst),Z1),
                                       empty(P,Z1,Z2) .

empty([],Z,Z) .

empty([X|L],Z1,Z2) :- holds(not peg(X),Z1), empty(L,Z1,Z2) .

strategy(Z1,Z2) :- board_solved(Z1,Z2) .

strategy(Z1,Z4) :- is_pattern(P,Z1,Z2),
                  pattern_solved(P,Z2,Z3),
                  strategy(Z3,Z4) .
```