



DEDUCTION SYSTEMS

Answer-Set Programming Motivation and Introduction

* slides adapted from Torsten Schaub [Gebser et al.(2012)]

Sarah Gaggl

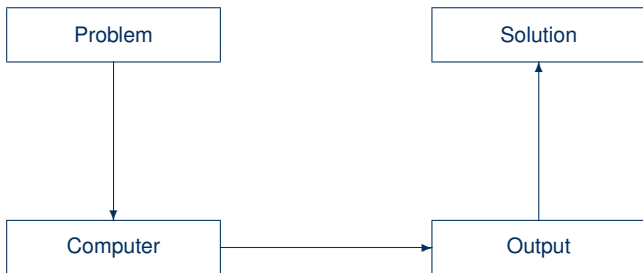
Dresden, 15 May 2014



Outline

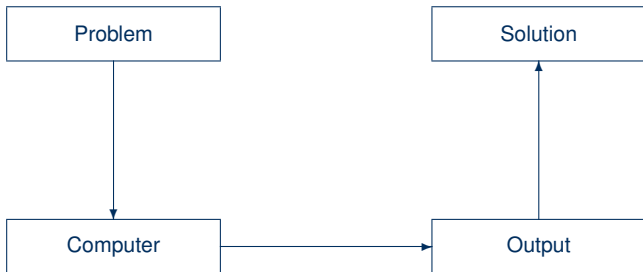
- 1 Motivation
 - Declarative Problem Solving
 - ASP in a Nutshell
 - ASP Paradigm
- 2 Introduction
 - Syntax
 - Semantics
 - Examples
 - Language Constructs
 - Modeling

Informatics



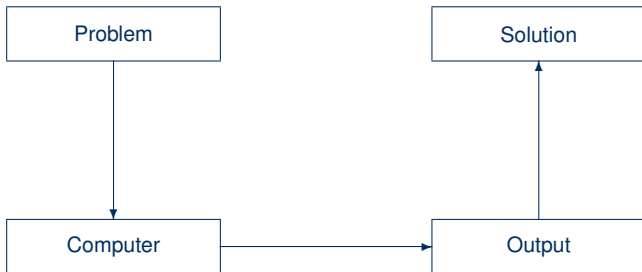
Informatics

“What is the problem?” versus “How to solve the problem?”



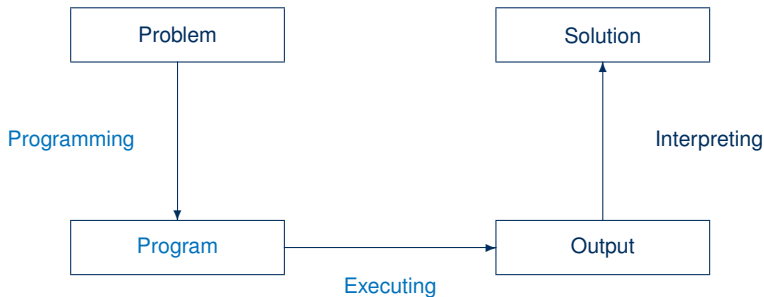
Traditional programming

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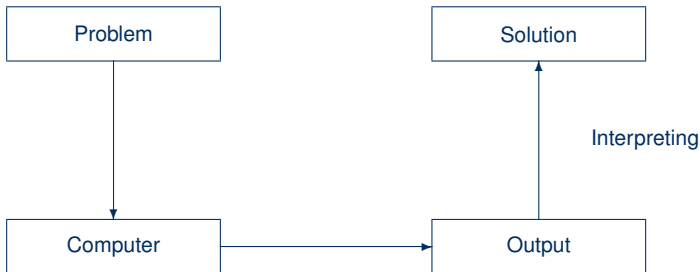
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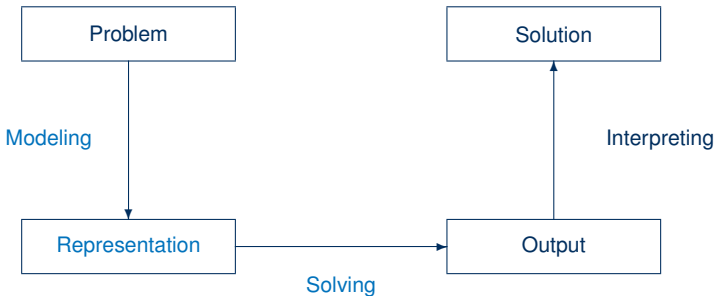
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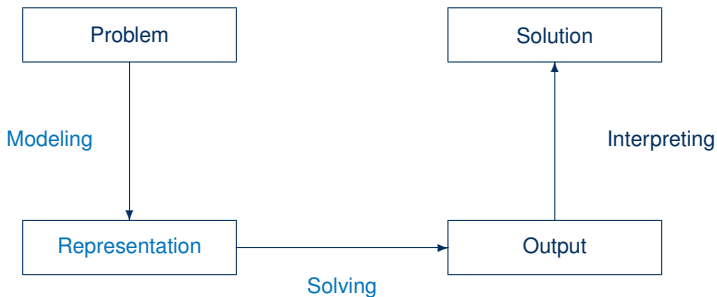


Declarative problem solving

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Declarative problem solving



Answer Set Programming

in a Nutshell

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 - a rich yet simple modeling language
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- ASP embraces many emerging application areas

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in a Hazelnutshell

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$$\mathbf{ASP = DB+LP+KR+SAT}$$

KR's shift of paradigm

Theorem Proving based approach (eg. Prolog)

- 1 Provide a representation of the problem
- 2 A solution is given by a **derivation** of a query

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- 2 A solution is given by a **model** of the representation

LP-style playing with blocks

Prolog program

```
on(a, b) .  
on(b, c) .
```

```
above(X, Y) :- on(X, Y) .  
above(X, Y) :- on(X, Z), above(Z, Y) .
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Prolog queries (testing entailment)

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no.
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LP-style playing with blocks

Shuffled Prolog program

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Prolog queries (answered via fixed execution)

```
?- above(a,c).  
  
Fatal Error: local stack overflow.
```

SAT-style playing with blocks

Formula

- $on(a, b)$
- $\wedge on(b, c)$
- $\wedge (on(X, Y) \rightarrow above(X, Y))$
- $\wedge (on(X, Z) \wedge above(Z, Y) \rightarrow above(X, Y))$

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Herbrand model

$$\left\{ \begin{array}{cccccc} on(a, b), & on(b, c), & on(a, c), & on(b, b), & & \\ above(a, b), & above(b, c), & above(a, c), & above(b, b), & above(c, b) & \end{array} \right\}$$

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➡ Answer Set Programming (ASP)

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Stable Herbrand model

```
{ on(a, b), on(b, c), above(b, c), above(a, b), above(a, c) }
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ASP-style playing with blocks

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ASP versus LP

ASP	Prolog
Model generation	Query orientation
Bottom-up	Top-down
Modeling language	Programming language
Rule-based format	
Instantiation Flat terms	Unification Nested terms
(Turing +) $NP^{(NP)}$	Turing

ASP versus SAT

ASP	SAT
Model generation	
Bottom-up	
Constructive Logic	Classical Logic
Closed (and open) world reasoning	Open world reasoning
Modeling language	—
Complex reasoning modes	Satisfiability testing
Satisfiability	Satisfiability
Enumeration/Projection	—
Optimization	—
Intersection/Union	—
(Turing +) $NP^{(NP)}$	NP

Two sides of a coin

- ASP as High-level Language
 - Express problem instance(s) as sets of facts
 - Encode problem (class) as a set of rules
 - Read off solutions from stable models of facts and rules
- ASP as Low-level Language
 - Compile a problem into a logic program
 - Solve the original problem by solving its compilation

What is ASP good for?

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- Combinatorial search problems in the realm of P , NP , and NP^{NP} (some with substantial amount of data), like
 - Automated Planning
 - Code Optimization
 - Composition of Renaissance Music
 - Database Integration
 - Decision Support for NASA shuttle controllers
 - Model Checking
 - Product Configuration
 - Robotics
 - System Biology
 - System Synthesis
 - (industrial) Team-building
 - and many many more

What does ASP offer?

- Integration of DB, KR, and SAT techniques
- Succinct, elaboration-tolerant problem representations
 - Rapid application development tool
- Easy handling of dynamic, knowledge intensive applications
 - including: data, frame axioms, exceptions, defaults, closures, etc

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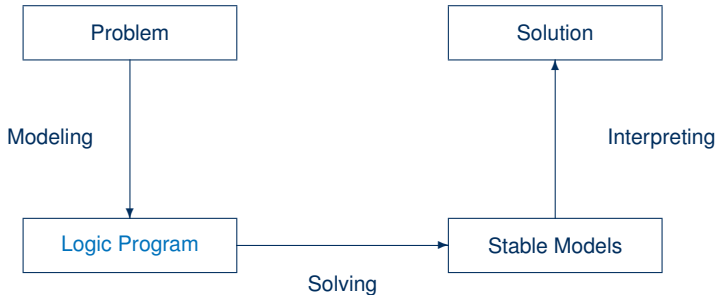
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Problem solving in ASP: Syntax



Normal logic programs

- A (normal) **logic program** over a set \mathcal{A} of atoms is a finite **set** of rules
- A (normal) **rule**, r , is of the form

$$a_0 \leftarrow a_1, \dots, a_m, \text{not } a_{m+1}, \dots, \text{not } a_n$$

where $0 \leq m \leq n$ and each $a_i \in \mathcal{A}$ is an atom for $0 \leq i \leq n$

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- Notation

$$\begin{aligned} \text{head}(r) &= a_0 \\ \text{body}(r) &= \{a_1, \dots, a_m, \text{not } a_{m+1}, \dots, \text{not } a_n\} \\ \text{body}(r)^+ &= \{a_1, \dots, a_m\} \\ \text{body}(r)^- &= \{a_{m+1}, \dots, a_n\} \end{aligned}$$

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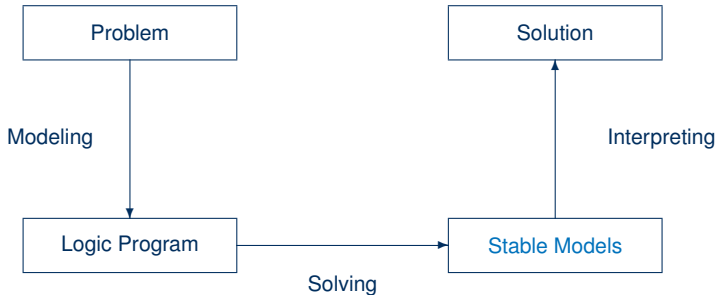
- A program is called **positive** if $\text{body}(r)^- = \emptyset$ for all its rules

Rough notational convention

We sometimes use the following notation interchangeably in order to stress the respective view:

	true, false	if	and	or	iff	default negation	classical negation
source code		<code>:-</code>	<code>,</code>	<code> </code>		<code>not</code>	<code>-</code>
logic program		<code>←</code>	<code>,</code>	<code>;</code>		<i>not</i>	\neg
formula	\perp, \top	\rightarrow	\wedge	\vee	\leftrightarrow	\sim	\neg

Problem solving in ASP: Semantics



Formal Definition

Stable models of positive programs

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- The set $Cn(P)$ of atoms is the **stable model** of a positive program P

Some “logical” remarks

- Positive rules are also referred to as **definite clauses**
 - Definite clauses are disjunctions with **exactly one** positive atom:

$$a_0 \vee \neg a_1 \vee \dots \vee \neg a_m$$

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- **Horn clauses** are clauses with **at most** one positive atom
 - Every definite clause is a Horn clause but not vice versa
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 - Non-definite Horn clauses can be regarded as integrity constraints
 - A set of Horn clauses has a **smallest model** or none
- This **smallest model** is the intended semantics of such sets of clauses
 - Given a positive program P , $Cn(P)$ corresponds to the smallest model of the set of definite clauses corresponding to P

Basic idea

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Consider the logical formula Φ and its three (classical) models:

$\{p, q\}$, $\{q, r\}$, and $\{p, q, r\}$

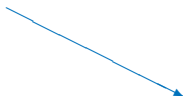
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$\{p, q\}$, $\{q, r\}$, and $\{p, q, r\}$



p	\mapsto	1
q	\mapsto	1
r	\mapsto	0

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Formula Φ has one stable model, often called **answer set**:

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Informally, a set X of atoms is a **stable model** of a logic program P

- if X is a (classical) model of P and
- if all atoms in X are **justified** by some rule in P

(rooted in intuitionistic logics HT (Heyting, 1930) and G3 (Gödel, 1932))

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Stable model of normal programs

- The [Gelfond-Lifschitz Reduct](#)[Gelfond and Lifschitz(1991)], P^X , of a program P relative to a set X of atoms is defined by

$$P^X = \{head(r) \leftarrow body(r)^+ \mid r \in P \text{ and } body(r)^- \cap X = \emptyset\}$$

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- A set X of atoms is a **stable model** of a program P , if $Cn(P^X) = X$
- Note: $Cn(P^X)$ is the \subseteq -smallest (classical) model of P^X
- Note: Every atom in X is justified by an “applying rule from P ”

A closer look at P^X

- In other words, given a set X of atoms from P ,

P^X is obtained from P by deleting

- 1 each rule having *not* a in its body with $a \in X$ and then
- 2 all negative atoms of the form *not* a in the bodies of the remaining rules

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- Note: Only *negative body literals* are evaluated w.r.t. X

A first example

$$P = \{p \leftarrow p, q \leftarrow \text{not } p\}$$

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X	P^X	$Cn(P^X)$
\emptyset	$p \leftarrow p$ $q \leftarrow$	$\{q\}$
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\emptyset	$p \leftarrow p$ $q \leftarrow$	$\{q\}$ x
$\{p\}$	$p \leftarrow p$	\emptyset x
$\{q\}$	$p \leftarrow p$ $q \leftarrow$	$\{q\}$
$\{p, q\}$	$p \leftarrow p$	\emptyset

A first example

$$P = \{p \leftarrow p, q \leftarrow \text{not } p\}$$

X	P^X	$Cn(P^X)$
\emptyset	$p \leftarrow p$ $q \leftarrow$	$\{q\}$ ✗
$\{p\}$	$p \leftarrow p$	\emptyset ✗
$\{q\}$	$p \leftarrow p$ $q \leftarrow$	$\{q\}$ ✓
$\{p, q\}$	$p \leftarrow p$	\emptyset

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A second example

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$\{p\}$	$p \leftarrow$	$\{p\}$
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$\{p\}$	$p \leftarrow$	$\{p\}$ ✓
$\{q\}$	$q \leftarrow$	$\{q\}$ ✓
$\{p, q\}$		\emptyset ✗

A third example

$$P = \{p \leftarrow \text{not } p\}$$

A third example

$$P = \{p \leftarrow \text{not } p\}$$

X	P^X	$Cn(P^X)$
\emptyset	$p \leftarrow$	$\{p\}$
$\{p\}$		\emptyset

A third example

$$P = \{p \leftarrow \text{not } p\}$$

X	P^X	$Cn(P^X)$
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$\{p\}$		\emptyset

A third example

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X	P^X	$Cn(P^X)$	
\emptyset	$p \leftarrow$	$\{p\}$	x
$\{p\}$		\emptyset	x

Some properties

- A logic program may have zero, one, or multiple stable models!

Some properties

- A logic program may have zero, one, or multiple stable models!
- If X is a stable model of a logic program P , then X is a model of P (seen as a formula)
- If X and Y are stable models of a normal program P , then $X \not\subseteq Y$

Programs with Variables

Let P be a logic program

- Let \mathcal{T} be a set of (variable-free) **terms**
- Let \mathcal{A} be a set of (variable-free) **atoms** constructable from \mathcal{T}

Programs with Variables

Let P be a logic program

- Let \mathcal{T} be a set of variable-free terms (also called Herbrand universe)
- Let \mathcal{A} be a set of (variable-free) atoms constructable from \mathcal{T} (also called alphabet or Herbrand base)

Programs with Variables

Let P be a logic program

- Let \mathcal{T} be a set of (variable-free) terms
- Let \mathcal{A} be a set of (variable-free) atoms constructable from \mathcal{T}
- **Ground Instances** of $r \in P$: Set of variable-free rules obtained by replacing all variables in r by elements from \mathcal{T} :

$$\text{ground}(r) = \{r\theta \mid \theta : \text{var}(r) \rightarrow \mathcal{T}, \text{var}(r\theta) = \emptyset\}$$

where $\text{var}(r)$ stands for the set of all variables occurring in r ;
 θ is a (ground) substitution

Programs with Variables

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where $\text{var}(r)$ stands for the set of all variables occurring in r ;
 θ is a (ground) substitution

- Ground Instantiation of P : $\text{ground}(P) = \bigcup_{r \in P} \text{ground}(r)$

An Example

$$P = \{ r(a, b) \leftarrow, r(b, c) \leftarrow, t(X, Y) \leftarrow r(X, Y) \}$$

$$\mathcal{T} = \{ a, b, c \}$$

$$\mathcal{A} = \left\{ \begin{array}{l} r(a, a), r(a, b), r(a, c), r(b, a), r(b, b), r(b, c), r(c, a), r(c, b), r(c, c), \\ t(a, a), t(a, b), t(a, c), t(b, a), t(b, b), t(b, c), t(c, a), t(c, b), t(c, c) \end{array} \right\}$$

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$$\text{ground}(P) = \left\{ \begin{array}{l} r(a, b) \leftarrow, \\ r(b, c) \leftarrow, \\ t(a, a) \leftarrow r(a, a), t(b, a) \leftarrow r(b, a), t(c, a) \leftarrow r(c, a), \\ t(a, b) \leftarrow r(a, b), t(b, b) \leftarrow r(b, b), t(c, b) \leftarrow r(c, b), \\ t(a, c) \leftarrow r(a, c), t(b, c) \leftarrow r(b, c), t(c, c) \leftarrow r(c, c) \end{array} \right\}$$

An Example

$$P = \{ r(a, b) \leftarrow, r(b, c) \leftarrow, t(X, Y) \leftarrow r(X, Y) \}$$

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$$\text{ground}(P) = \left\{ \begin{array}{l} r(a, b) \leftarrow, \\ r(b, c) \leftarrow, \\ t(a, b) \leftarrow, \\ t(b, c) \leftarrow \end{array} \right\}$$

- Intelligent Grounding aims at reducing the ground instantiation

Stable models of programs with Variables

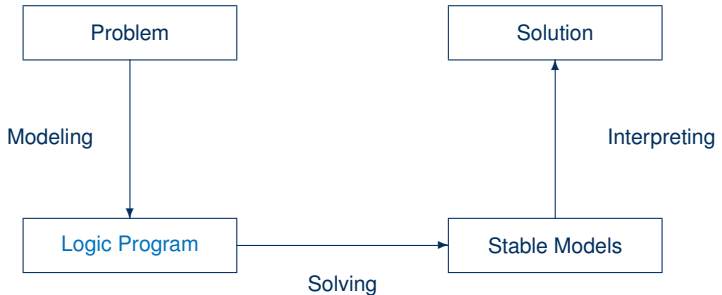
Let P be a normal logic program with variables

Stable models of programs with Variables

Let P be a normal logic program with variables

- A set X of (ground) atoms is a stable model of P ,
if $Cn(\text{ground}(P)^X) = X$

Problem solving in ASP: Extended Syntax



Language Constructs

Language Constructs

- Variables (over the Herbrand Universe)
 - $p(X) :- q(X)$ over constants $\{a,b,c\}$ stands for
 $p(a) :- q(a), p(b) :- q(b), p(c) :- q(c)$

Language Constructs

- Conditional Literals

- $p :- q(X) : r(X)$ given $r(a), r(b), r(c)$ stands for
 $p :- q(a), q(b), q(c)$

Language Constructs

- Disjunction

– $p(X) \mid q(X) :- r(X)$

Language Constructs

- Integrity Constraints
 - $\text{:- } q(X), p(X)$

Language Constructs

- Choice

- $2 \{ p(X, Y) : q(X) \} \vdash :- r(Y)$

Language Constructs

- Aggregates

- `s(Y) :- r(Y), 2 #count { p(X,Y) : q(X) } 7`
- also: `#sum, #avg, #min, #max, #even, #odd`

Language Constructs

- **Variables** (over the Herbrand Universe)
 - $p(X) :- q(X)$ **over constants** $\{a,b,c\}$ stands for
 $p(a) :- q(a), p(b) :- q(b), p(c) :- q(c)$
- **Conditional Literals**
 - $p :- q(X) : r(X)$ **given** $r(a), r(b), r(c)$ stands for
 $p :- q(a), q(b), q(c)$
- **Integrity Constraints**
 - $:- q(X), p(X)$
- **Choice**
 - $2 \{ p(X,Y) : q(X) \} 7 :- r(Y)$
- **Aggregates**
 - $s(Y) :- r(Y), 2 \#count \{ p(X,Y) : q(X) \} 7$
 - **also:** $\#sum, \#avg, \#min, \#max, \#even, \#odd$

Modeling

- For solving a problem class C for a problem instance I , encode
 - 1 the problem instance I as a set P_I of facts and
 - 2 the problem class C as a set P_C of rulessuch that the solutions to C for I can be (polynomially) extracted from the stable models of $P_I \cup P_C$

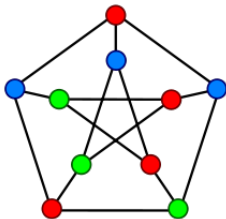
Modeling

- For solving a problem class \mathbf{C} for a problem instance \mathbf{I} , encode
 - 1 the problem instance \mathbf{I} as a set $P_{\mathbf{I}}$ of facts and
 - 2 the problem class \mathbf{C} as a set $P_{\mathbf{C}}$ of rulessuch that the solutions to \mathbf{C} for \mathbf{I} can be (polynomially) extracted from the stable models of $P_{\mathbf{I}} \cup P_{\mathbf{C}}$
- $P_{\mathbf{I}}$ is (still) called **problem instance**
- $P_{\mathbf{C}}$ is often called the **problem encoding**

Modeling

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- $P_{\mathbf{I}}$ is (still) called **problem instance**
- $P_{\mathbf{C}}$ is often called the **problem encoding**
- An **encoding** $P_{\mathbf{C}}$ is **uniform**, if it can be used to solve all its problem instances
That is, $P_{\mathbf{C}}$ encodes the solutions to \mathbf{C} for any set $P_{\mathbf{I}}$ of facts

Example 3-Colorability



- Vertices are represented with predicates $\text{node}(X)$;
- Edges are represented with predicates $\text{edge}(X, Y)$.

Question: Is there a valid assignment of three colors for an input graph G such that no two adjacent vertices have the same color?

Graph coloring

node (1..6) .

Graph coloring

node (1..6) .

edge (1, 2) . edge (1, 3) . edge (1, 4) .

edge (2, 4) . edge (2, 5) . edge (2, 6) .

edge (3, 1) . edge (3, 4) . edge (3, 5) .

edge (4, 1) . edge (4, 2) .

edge (5, 3) . edge (5, 4) . edge (5, 6) .

edge (6, 2) . edge (6, 3) . edge (6, 5) .

Graph coloring

node (1..6) .

edge (1, 2) . edge (1, 3) . edge (1, 4) .

edge (2, 4) . edge (2, 5) . edge (2, 6) .

edge (3, 1) . edge (3, 4) . edge (3, 5) .

edge (4, 1) . edge (4, 2) .

edge (5, 3) . edge (5, 4) . edge (5, 6) .

edge (6, 2) . edge (6, 3) . edge (6, 5) .

col (r) . col (b) . col (g) .

Graph coloring

node (1..6) .

edge (1, 2) . edge (1, 3) . edge (1, 4) .

edge (2, 4) . edge (2, 5) . edge (2, 6) .

edge (3, 1) . edge (3, 4) . edge (3, 5) .

edge (4, 1) . edge (4, 2) .

edge (5, 3) . edge (5, 4) . edge (5, 6) .

edge (6, 2) . edge (6, 3) . edge (6, 5) .

col (r) . col (b) . col (g) .

Graph coloring

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edge (1, 2) . edge (1, 3) . edge (1, 4) .

edge (2, 4) . edge (2, 5) . edge (2, 6) .

edge (3, 1) . edge (3, 4) . edge (3, 5) .

edge (4, 1) . edge (4, 2) .

edge (5, 3) . edge (5, 4) . edge (5, 6) .

edge (6, 2) . edge (6, 3) . edge (6, 5) .

col (r) . col (b) . col (g) .

**Problem
instance**

Graph coloring

```
node (1..6) .
```

```
edge (1,2) .   edge (1,3) .   edge (1,4) .
```

```
edge (2,4) .   edge (2,5) .   edge (2,6) .
```

```
edge (3,1) .   edge (3,4) .   edge (3,5) .
```

```
edge (4,1) .   edge (4,2) .
```

```
edge (5,3) .   edge (5,4) .   edge (5,6) .
```

```
edge (6,2) .   edge (6,3) .   edge (6,5) .
```

```
col(r) .   col(b) .   col(g) .
```

```
1 { color(X,C) : col(C) } 1 :- node(X) .
```

Graph coloring

```
node(1..6).
```

```
edge(1,2). edge(1,3). edge(1,4).
```

```
edge(2,4). edge(2,5). edge(2,6).
```

```
edge(3,1). edge(3,4). edge(3,5).
```

```
edge(4,1). edge(4,2).
```

```
edge(5,3). edge(5,4). edge(5,6).
```

```
edge(6,2). edge(6,3). edge(6,5).
```

```
col(r). col(b). col(g).
```

```
1 { color(X,C) : col(C) } 1 :- node(X).
```

```
:- edge(X,Y), color(X,C), color(Y,C).
```

Graph coloring

```
node(1..6).
```

```
edge(1,2). edge(1,3). edge(1,4).
```

```
edge(2,4). edge(2,5). edge(2,6).
```

```
edge(3,1). edge(3,4). edge(3,5).
```

```
edge(4,1). edge(4,2).
```

```
edge(5,3). edge(5,4). edge(5,6).
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1 { color(X,C) : col(C) } 1 :- node(X).
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```

} **Problem
encoding**

Graph coloring

```
node(1..6).
```

```
edge(1,2). edge(1,3). edge(1,4).
```

```
edge(2,4). edge(2,5). edge(2,6).
```

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edge(3,1). edge(3,4). edge(3,5).
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edge(4,1). edge(4,2).
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edge(5,3). edge(5,4). edge(5,6).
```

```
edge(6,2). edge(6,3). edge(6,5).
```

```
col(r). col(b). col(g).
```

} Problem
instance

```
1 { color(X,C) : col(C) } 1 :- node(X).
```

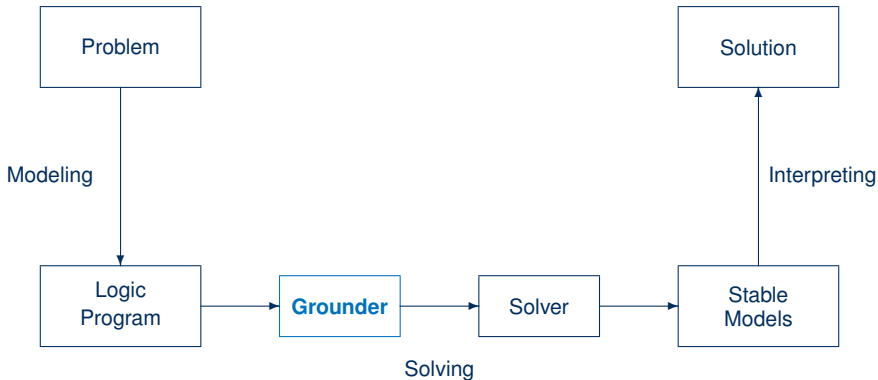
```
:- edge(X,Y), color(X,C), color(Y,C).
```

} Problem
encoding

color.lp

```
node(1..6).  
  
edge(1,2).  edge(1,3).  edge(1,4).  
edge(2,4).  edge(2,5).  edge(2,6).  
edge(3,1).  edge(3,4).  edge(3,5).  
edge(4,1).  edge(4,2).  
edge(5,3).  edge(5,4).  edge(5,6).  
edge(6,2).  edge(6,3).  edge(6,5).  
  
col(r).    col(b).    col(g).  
  
1 { color(X,C) : col(C) } 1 :- node(X).  
  
:- edge(X,Y), color(X,C), color(Y,C).
```

ASP solving process



Graph coloring: Grounding

```
$ gringo --text color.lp
```

Graph coloring: Grounding

```
$ gringo --text color.lp
```

```
node(1). node(2). node(3). node(4). node(5). node(6).
```

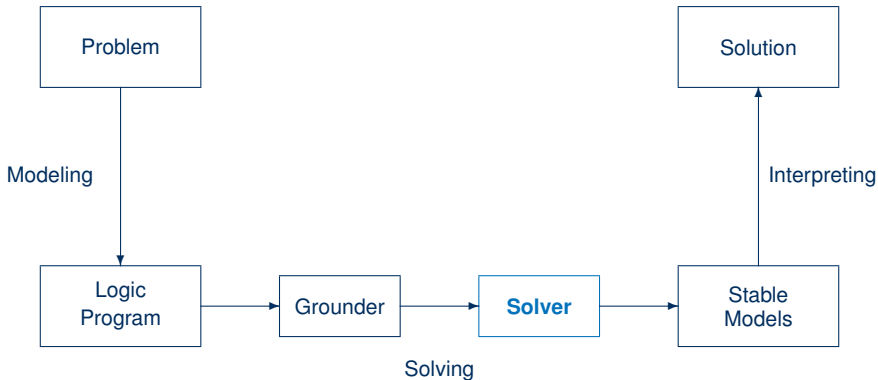
```
edge(1,2). edge(1,3). edge(1,4). edge(2,4). edge(2,5). edge(2,6).
edge(3,1). edge(3,4). edge(3,5). edge(4,1). edge(4,2). edge(5,3).
edge(5,4). edge(5,6). edge(6,2). edge(6,3). edge(6,5).
```

```
col(r). col(b). col(g).
```

```
1 {color(1,r), color(1,b), color(1,g)} 1.
1 {color(2,r), color(2,b), color(2,g)} 1.
1 {color(3,r), color(3,b), color(3,g)} 1.
1 {color(4,r), color(4,b), color(4,g)} 1.
1 {color(5,r), color(5,b), color(5,g)} 1.
1 {color(6,r), color(6,b), color(6,g)} 1.
```

```
:- color(1,r), color(2,r). :- color(2,g), color(5,g). ... :- color(6,r), color(2,r).
:- color(1,b), color(2,b). :- color(2,r), color(6,r). :- color(6,b), color(2,b).
:- color(1,g), color(2,g). :- color(2,b), color(6,b). :- color(6,g), color(2,g).
:- color(1,r), color(3,r). :- color(2,g), color(6,g). :- color(6,r), color(3,r).
:- color(1,b), color(3,b). :- color(3,r), color(1,r). :- color(6,b), color(3,b).
:- color(1,g), color(3,g). :- color(3,b), color(1,b). :- color(6,g), color(3,g).
:- color(1,r), color(4,r). :- color(3,g), color(1,g). :- color(6,r), color(5,r).
:- color(1,b), color(4,b). :- color(3,s), color(4,r). :- color(6,b), color(5,b).
:- color(1,g), color(4,g). :- color(3,b), color(4,b). :- color(6,g), color(5,g).
:- color(2,r), color(4,r). :- color(3,g), color(4,g).
:- color(2,b), color(4,b). :- color(3,r), color(5,r).
```

ASP solving process



Graph coloring: Solving

```
$ gringo color.lp | clasp 0
```

Graph coloring: Solving

```
$ gringo color.lp | clasp 0
```

```
clasp version 2.1.0
Reading from stdin
Solving...
Answer: 1
edge(1,2) ... col(r) ... node(1) ... color(6,b) color(5,g) color(4,b) color(3,r) color(2,r)
Answer: 2
edge(1,2) ... col(r) ... node(1) ... color(6,r) color(5,g) color(4,r) color(3,b) color(2,b)
Answer: 3
edge(1,2) ... col(r) ... node(1) ... color(6,g) color(5,b) color(4,g) color(3,r) color(2,r)
Answer: 4
edge(1,2) ... col(r) ... node(1) ... color(6,r) color(5,b) color(4,r) color(3,g) color(2,g)
Answer: 5
edge(1,2) ... col(r) ... node(1) ... color(6,g) color(5,r) color(4,g) color(3,b) color(2,b)
Answer: 6
edge(1,2) ... col(r) ... node(1) ... color(6,b) color(5,r) color(4,b) color(3,g) color(2,g)
SATISFIABLE

Models      : 6
Time       : 0.002s (Solving: 0.00s 1st Model: 0.00s Unsat: 0.00s)
CPU Time   : 0.000s
```

Reasoning Modes

- Satisfiability
- Enumeration[†]
- Projection[†]
- Intersection[‡]
- Union[‡]
- Optimization
- and combinations of them

[†] without solution recording

[‡] without solution enumeration

References



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- See also: <http://potassco.sourceforge.net>