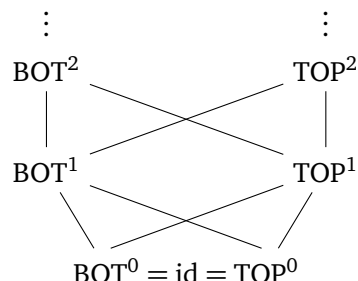


## Advanced Topics on Weighted Tree Automata

*Exercise 27* ( $BOT^n \subseteq TOP^{n+1}$  and  $TOP^n \subseteq BOT^{n+1}$ )

Using the fact that  $\forall n \geq 1: BOT^n \circledcirc TOP^n$  [Eng82], prove the correctness of the following Hasse-diagram:



*Exercise 28* (Top-down tree transducer with regular look-ahead)

Let  $T = (Q, \Sigma, \Delta, I, R)$  be a top-down tree transducer with regular look-ahead.

- Give a formal definition of the derivation relation of  $T$ .
- Give a formal definition of the tree transformation induced by  $T$ .

*Exercise 29* ( $TOP^R \subseteq d\text{-QREL} \circ TOP$ )

Let  $L_1, \dots, L_n \in \text{REC}(\Sigma)$  be recognizable tree languages,  $\mathcal{U} = \{0, 1\}^n$ , and  $\Sigma$  and  $\Omega$  be ranked alphabets where  $\Omega = \{ \langle \sigma, (u_1, \dots, u_k) \rangle^{(k)} \mid \sigma \in \Sigma, \text{rk}(\sigma) = k, u_1, \dots, u_k \in \mathcal{U} \}$ . Note that if  $k = 0$  we write  $\sigma$  rather than  $\langle \sigma, () \rangle$ . Consider the recursively defined non-deterministic total function  $B_{L_1, \dots, L_n}: T_\Sigma \rightarrow \mathcal{P}(T_\Omega)$  where for every  $\sigma \in \Sigma$  and  $t_1, \dots, t_k \in T_\Sigma$ :

$$B_{L_1, \dots, L_n}(\sigma(t_1, \dots, t_k)) = \{ \langle \sigma, (u_1, \dots, u_k) \rangle (t'_1, \dots, t'_k) \mid t'_1 \in B_{L_1, \dots, L_n}(t_1), \dots, t'_k \in B_{L_1, \dots, L_n}(t_k), \\ \forall i \in [k], \forall j \in [n]: u_i \in \mathcal{U}, u_i(j) = \text{if } t_i \in L_j \text{ then } 1 \text{ else } 0 \}$$

- Give a deterministic state-relabeling bu-tt  $B$  that computes  $B_{L_1, \dots, L_n}$ .
- Let  $\Sigma = \{ \sigma^{(2)}, \gamma^{(1)}, \alpha^{(0)}, \beta^{(0)} \}$  be a ranked alphabet,  $n = 2$ , and  $L_1 = \{ \gamma^k(\beta) \mid k \in \mathbb{N} \}$  and  $L_2 = \{ \gamma^k(\alpha) \mid k \in \mathbb{N} \}$  be recognizable tree languages. Construct a deterministic state-relabeling bu-tt  $B'$  that computes  $B_{L_1, L_2}$ .

*Exercise 30* ( $l\text{-BOT} = l\text{-TOP}^R$ )

Consider the linear bu-tt  $B = (Q, \Sigma, \Delta, F, R)$  where  $\Sigma = \Delta = \{ \sigma^{(2)}, \gamma^{(1)}, \alpha^{(0)}, \beta^{(0)} \}$ ,  $Q = \{ *, q, q_f \}$ ,  $F = \{ q_f \}$ , and

$$R = \{ \alpha \rightarrow q(\alpha), \quad \alpha \rightarrow *(\alpha), \quad \beta \rightarrow *(\beta), \\ \gamma(q(x_1)) \rightarrow q(\gamma(x_1)), \quad \gamma(*(\alpha)) \rightarrow *(\gamma(x_1)), \\ \sigma(*(\alpha), q(x_2)) \rightarrow q_f(x_1), \quad \sigma(*(\alpha), *(x_2)) \rightarrow *(\sigma(x_1, x_2)) \}$$

- Give a linear td-tt with regular look-ahead  $T$  such that  $\tau(T) = \tau(B)$ .
- Construct a deterministic state-relabeling bu-tt  $B'$  and a linear td-tt  $T'$  such that  $\tau(T) = \tau(B') \circ \tau(T')$ .

## References

[Eng82] J. Engelfriet. Three hierarchies of transducers. *Math. Systems Theory*, 15(2):95–125, 1982.